

Analog Computing Techniques Applied to Atmospheric Diffusion : Continuous Point Source^{1,2,3}

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ABSTRACT

The analog computer has been used to obtain solutions to the diffusion equation for the case of a continuous point source aloft. The basic model used is that of a source located between an inversion and the ground where the wind speed and eddy diffusivity are constant over the diffusing region. Solutions were also obtained with several special features added to the basic model: representation of the eddy diffusivity as a function of distance downstream; presence of wind direction shear in the diffusing layers; and the presence of large-scale eddies which cause the meandering of the plume.

The solutions are presented as deviations from the reference solution, that solution derived from the basic model, to show graphically the effects of each parameter change.

1. Introduction

Turbulent diffusion from an elevated point source is of primary concern in air-pollution meteorology. Although such diffusion is the central component of a common problem, it is by no means a well-understood phenomenon. This results in part from the lack of a sufficiently general mathematical model with a complete set of solutions. No matter how well diffusion is documented in the field, it cannot be completely and compactly expressed and understood except in reference to such a model. But atmospheric diffusion is such an intricate mechanism that no one model is very likely to satisfy all demands.

One model which is perhaps sufficiently general is the parabolic diffusion equation

$$\frac{d\chi}{dt} = \frac{\partial}{\partial x} \left[K_x \frac{\partial \chi}{\partial x} \right] + \frac{\partial}{\partial y} \left[K_y \frac{\partial \chi}{\partial y} \right] + \frac{\partial}{\partial z} \left[K_z \frac{\partial \chi}{\partial z} \right], \quad (1)$$

where

$$\frac{d\chi}{dt} = u \frac{\partial \chi}{\partial x} + v \frac{\partial \chi}{\partial y} + w \frac{\partial \chi}{\partial z} + \frac{\partial \chi}{\partial t}$$

and

χ = average concentration

x, y, z = space coordinates

u, v, w = average wind components

K_i = coefficient of eddy diffusivity in the i -direction

t = time.

This model has two main shortcomings: it yields only average concentration, and a complete set of solutions has not been found. In fact, such analytical solutions as are available apply only to special cases of limited application as described by Sutton (1953) and Godson (1958). Another deficiency is that the model implies an infinite diffusing velocity, but in cases where this is important, the hyperbolic diffusion equation can be used (Goldstein, 1951). In the case of steady-state diffusion, the velocity of diffusion is not important.

The validity of the application of the parabolic diffusion equation to atmospheric diffusion has been questioned, but the lack of adequate solutions has made verification difficult. The use of electronic computing machines makes solutions available for any type of parameter variation but here another difficulty arises. Since analytical solutions are not readily available, the functional dependence of some of the parameters has not been determined. For example, Richardson (1926) has suggested that the coefficient of eddy diffusivity be a function of plume size, but the exact form of this function has not been indicated.

The purpose of this paper is to show how the diffusion equation may be implemented on the electronic analog computer and to show the qualitative nature of the solutions. Means for obtaining improved solution accuracy are also indicated. The reasons for using the analog computer in this application are that it is easy to program and that it presents the solution in graphical form.

The problems chosen for solution are based upon the

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case of diffusion in the steady-state from a point source located half-way between the surface of the ground and the base of an inversion. The special cases considered here were selected from the many problems of interest described elsewhere by Hewson (1951, 1956, 1963). The methods outlined are perfectly general, however, and with an analog computer of sufficient capacity, a similar analysis may be made for nearly any meteorological conditions. Added to the basic model are several functions of the average wind components and the coefficients of eddy diffusivity so as to consider the case of a plume passing from one turbulent regime to another, the theoretical question of making the diffusivity a function of cloud size, the case of wind direction shear with height in the diffusing region, and the case of the meandering plume. The model is arranged so that the origin is at the source, the x -axis oriented downwind, the y -axis crosswind, and the z -axis vertical. The basic model includes no provision for variations in the wind speed with height or in the eddy diffusivity in the y - or z -directions. These can be readily provided but the emphasis here is on special techniques.

2. Finite difference model

The model presented in Eq (1) can be simplified by deleting the terms that do not apply, to

$$u \frac{\partial \chi}{\partial x} = K \frac{\partial^2 \chi}{\partial y^2} + K \frac{\partial^2 \chi}{\partial z^2} - v \frac{\partial \chi}{\partial y}, \tag{2}$$

where the diffusion term in x was neglected in comparison to the transport term in x . In all cases the eddy diffusivity is taken to be the same in all directions. The boundary conditions are

$$\begin{aligned} \chi \rightarrow \infty & \quad \text{as} \quad x, y \rightarrow 0; \quad z \rightarrow \text{source height} \\ \chi \rightarrow 0 & \quad \text{as} \quad x, y, z \rightarrow \infty \\ K \frac{\partial \chi}{\partial z} \rightarrow 0 & \quad \text{as} \quad z \rightarrow -\frac{H}{2}, +\frac{H}{2} \quad \text{for} \quad x > 0, \end{aligned}$$

where H is the height above ground of the base of the inversion layer. These conditions state that the concentration is infinite at the source and that the ground and the inversion are impervious to the diffusing substance. The continuity condition is

$$\int_{-\infty}^{\infty} \int_{-H/2}^{+H/2} u \chi(x, y, z) dz dy = Q \quad \text{for} \quad x > 0, \tag{3}$$

where Q is the rate of emission from the source. It is convenient to state (2) in nondimensional form

$$\frac{\partial S}{\partial \bar{x}} = \frac{\partial^2 S}{\partial Y^2} + \frac{\partial^2 S}{\partial Z^2} - V \frac{\partial S}{\partial Y}, \tag{4}$$

where

$$\begin{aligned} S &= \chi / \chi_0 \\ Y &= y / H \\ Z &= z / H \\ \bar{x} &= Kx / uH^2 \\ V &= Hv / K \end{aligned}$$

and the symbol X is reserved for later use. The constant χ_0 will be defined later.

The mathematical model to be used, Eq (4), must be put in a form suitable for programming on the analog computer. Since the computer can integrate only with respect to one independent variable, computer time, two of the independent variables must be replaced with finite differences. The derivatives in Y and Z will be expressed as finite differences as follows

$$\begin{aligned} \frac{\partial^2 S}{\partial Y^2} \Big|_m &= \frac{1}{\Delta Y(m)} \left[\frac{S(m+1) - S(m)}{\Delta Y(m+\frac{1}{2})} - \frac{S(m) - S(m-1)}{\Delta Y(m-\frac{1}{2})} \right] \\ \frac{\partial S}{\partial Y} \Big|_m &= \frac{S(m+1) - S(m-1)}{2\Delta Y(m)} \\ \frac{\partial^2 S}{\partial Z^2} \Big|_n &= \frac{S(n+1) - 2S(n) + S(n-1)}{\Delta Z^2}. \end{aligned} \tag{5}$$

The expressions for the second derivatives in Y and Z are different because, in all the cases studied here, uniform differences were taken in z but nonuniform differences are taken in Y . If uniform differences were taken both ways, the two expressions would be identical. Eq (4) may now be stated as a set of simultaneous, ordinary differential equations

$$\begin{aligned} \frac{dS}{d\bar{x}} \Big|_{m,n} &= \frac{1}{\Delta Y(m)} \left[\frac{S(m+1,n) - S(m,n)}{\Delta Y(m+\frac{1}{2})} \right. \\ &\quad \left. - \frac{S(m,n) - S(m-1,n)}{\Delta Y(m-\frac{1}{2})} \right] \\ &\quad + \frac{S(m,n+1) - 2S(m,n) + S(m,n-1)}{\Delta Z^2} \\ &\quad - V \frac{S(m+1,n) - S(m-1,n)}{2\Delta Y(m)}, \end{aligned} \tag{6}$$

where the indices m and n refer to discrete values in Y and Z , respectively. The physical model corresponding to Eq (6) is shown in Fig. 1. This is the particular model that will be used in the section on computation in connection with the isotropic diffusion case. It consists of an array of cells of rectangular cross section with width ΔY , height ΔZ , and with one end at $\bar{x}=0$ and the other at $\bar{x}=\infty$. The cells are stacked vertically from the ground to the inversion base and horizontally from $-\infty$

to $+\infty$. The number of cells in Y is finite since the end cells have width $\Delta Y = \infty$. The source cells are in the center of the array and are designated $\pm 1, \pm 1$.

All the properties of each cell are lumped in the center of the cross section so that the model is an array of rods with one end at $\bar{x} = 0$ and the other at $\bar{x} = \infty$. The source is no longer a point source but a vertical area source. In this model, the continuity Eq (3) holds for all values of \bar{x} , and by evaluating it at $\bar{x} = 0$, we can define χ_0 .

$$Q = \int_{Y_1}^{Y_2} \int_{Z_1}^{Z_2} H^2 u S \chi_0 dZ dY.$$

The integration at $\bar{x} = 0$ is carried over the source cell only, and in a given cell all the parameters in the

integrand are constant. Since the value of S at $\bar{x} = 0$ in the source is set at unity,

$$Q = H^2 u \chi_0 \Delta Y (1) \Delta Z (1)$$

and therefore

$$\chi_0 = \frac{Q}{u H^2 \Delta Y (1) \Delta Z (1)}.$$

This is the only use made of the continuity equation in this model. The solutions that will be obtained with this model will be the average concentration over the cross section of a cell as a function of its length, or distance downwind.

3. Computation and results

Since each of the cases considered is quite different, the form of Eq (6) appropriate to each will be given along with the computing circuit and the results.

A. Isotropic diffusion with an 84-cell model. The first case is diffusion from the point source in isotropic conditions, that is, the wind speed and eddy diffusivity are constant over the region. The 84-cell model used is shown in Fig. 1. It is symmetrical about the coordinate axis so only the cells in the first quadrant need be simulated and of these, the ones in the outer column, $m = 3$, are always zero so that there are only 14 active cells in the simulation. In this case, Eq (6) becomes

$$\frac{dS}{dX} \Big|_{m,n} = \frac{1}{196 \Delta Y (m)} \left[\frac{S(m+1,n) - S(m,n)}{\Delta Y (m + \frac{1}{2})} - \frac{S(m,n) - S(m-1,n)}{\Delta Y (m - \frac{1}{2})} \right] + \frac{S(m,n+1) - 2S(m,n) + S(m,n-1)}{196 (\Delta Z)^2}, \quad (7)$$

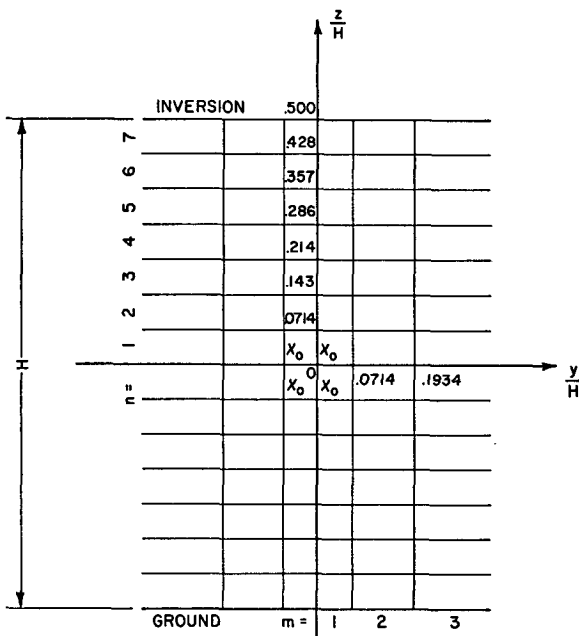


FIG. 1. The 84-cell, finite difference model of isotropic diffusion from a point source.

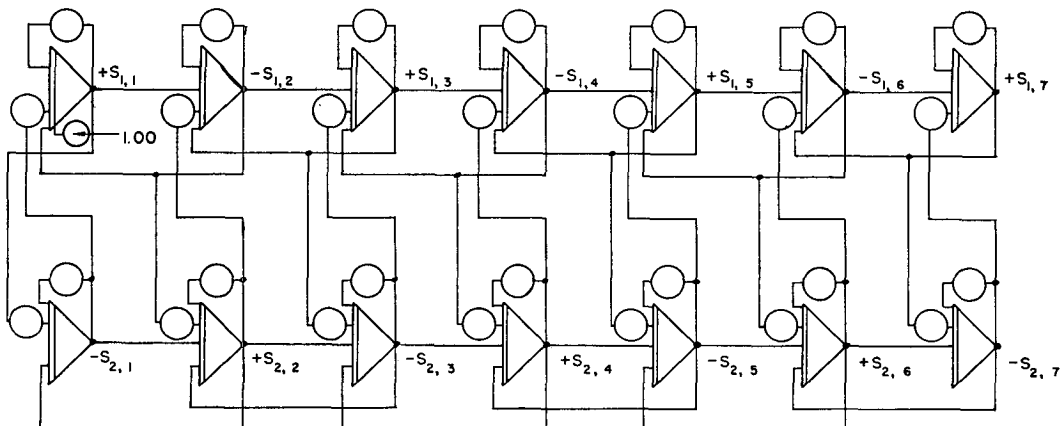


FIG. 2. Computing circuit for the first quadrant of the 84-cell model.

where $X=196\bar{x}$ and the boundary conditions are

$$\begin{aligned} S(1,n) &= S(-1, n) \\ S(m,1) &= S(m, -1) \\ S(1,1)|_0 &= 1.00 \\ S(3,n) &= 0 \\ S(m,7) &= S(m,8). \end{aligned}$$

The factor 196 was inserted to make the coefficients more convenient. The cell boundaries given in Table 1 show that the spacing in the vertical is linear whereas the spacing in the horizontal is exponential and the source cell has a square cross section.

Since ΔZ is a constant for each cell, Eq (7) can be conveniently expressed as two sets of simultaneous, ordinary differential equations for the columns used.

$$\begin{aligned} \left. \frac{dS}{dX} \right|_{1,n} &= 0.8228[S(2,n) - S(1,n)] \\ &\quad + [S(1,n+1) - 2S(1,n) + S(1,n-1)] \\ \left. \frac{dS}{dX} \right|_{2,n} &= 0.4937S(1,n) - 0.7410S(2,n) \\ &\quad + [S(2,n+1) - 2S(2,n) + S(2,n-1)]. \end{aligned} \quad (8)$$

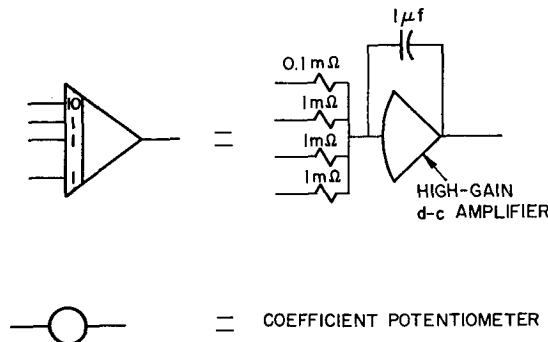
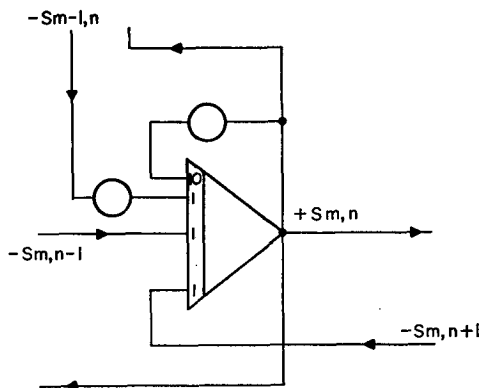


FIG. 3. Typical cell from the circuit of Fig. 2 showing the connections to the integrating amplifier.

TABLE 1. Cell boundaries in the horizontal and the vertical for the first quadrant of the 84-cell model.

$Y=y/H$	$Z=z/H$
0	0
0.0714	0.0714
0.1934	0.1428
∞	0.2142
	0.2856
	0.3570
	0.4284
	0.5000

The computer circuit for Eq (8) which is shown in Fig. 2 has one amplifier for each of the 14 differential equations represented by (8). The top row of amplifiers simulates the first column of cells and the top equation in (8). The bottom equation is solved by the lower row of amplifiers. The $S(1,1)$ amplifier in the top row represents the source cell and has an initial condition of $S=1.00$ at computer time (distance in X) $t=0$. The basic unit of computation is the integrating amplifier as shown in Fig. 3 for a typical cell. Solution curves for the first row of cells are shown in Figs. 4 and 5. After Eq (8) is reduced to the form

$$\begin{aligned} \left. \frac{dS}{dX} \right|_{m,n} &= aS(m,n+1) + bS(m,n-1) - cS(m,n) \\ &\quad + dS(m+1,n) + eS(m-1,n) \end{aligned} \quad (9)$$

the coefficients a through e are used to implement the circuit diagrams. For this problem, the numerical values of a through e are given in Table 2. Since coefficients

TABLE 2. Numerical values of coefficients to be applied to the coefficient potentiometers in the computer diagram.

m	a	b	c	d	e
1	1.00	1.00	2.8228	0.8228	0
2	1.00	1.00	2.7410	0	0.7410

a and b are unity, no coefficient potentiometer is needed for the associated connection. Note that in Fig. 3 the leads labeled $S(m, n+1)$ and $S(m, n-1)$ go directly to the integrator. If a coefficient is zero, no connection is made. The non-unity and non-zero coefficients are set with a potentiometer as indicated in Figs. 2 and 3.

The solution is displayed in Figs. 4 and 5. To interpret these figures, the dimensionless parameters must be evaluated in terms of real physical units. The following relations hold throughout the paper: $\chi = QS/uH^2\Delta Y(n)\Delta Z(n)$, $x = H^2u\bar{x}/K$, $y = HY$, $z = HZ$, and $v = KV/H$, where n indicates the source cell. In this problem, $\Delta Y(n) = \Delta Z(n) = 0.0714$ and $\bar{x} = X/196$ so that $\chi = 196QS/uH^2$ and $x = H^2uX/196K$. Evaluation of these coefficients requires knowledge of the mean

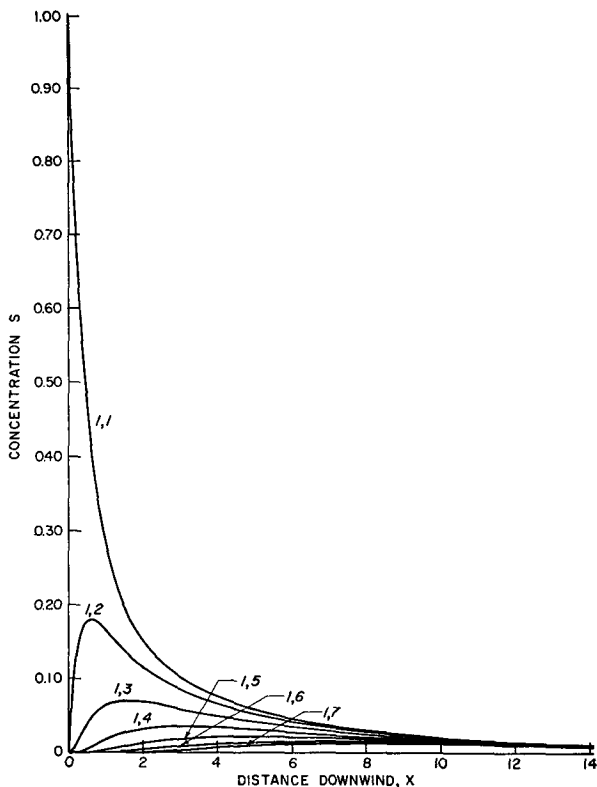


FIG. 4. Concentration plots for each cell as a function of distance downwind from a point source using the 84-cell model in isotropic conditions.

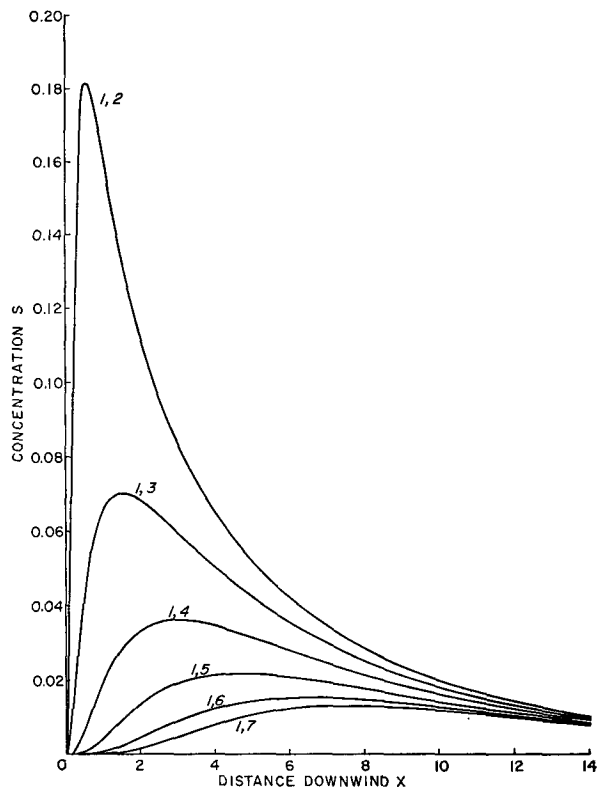


FIG. 5. Concentration plots for each cell as a function of distance downwind from a point source using the 84-cell model in isotropic conditions.

wind speed and eddy diffusivity, height of the inversion and source strength.

B. Isotropic diffusion with a 56-cell model. To facilitate the simulation, the number of cells can be reduced. In this case, only 4 cells in Y are to be used instead of 6. The purpose of this reduction is that more involved problems to be treated are more readily handled with a simpler basic model. Not so much equipment is needed in this case but the reduction in the number of cells imposes a severe accuracy penalty. Before introducing the more interesting cases, the magnitude of the error introduced can be shown by solving the same problem employing the same techniques.

Cell boundaries in Y for the 56-cell model are $Y=0, 0.0714, \infty$; while the cell boundaries in Z are as stated in Table 1. In the first quadrant, there are still 7 active cells in Z but only 1 in Y ; thus there is 1 active column and Eq (8) simplifies to

$$\left. \frac{dS}{dX} \right|_{1,n} = -0.7220S(1,n) + [S(1,n+1) - 2S(1,n) + S(1,n-1)], \quad (10)$$

where $X=196\bar{x}$ and the boundary conditions are

$$\begin{aligned} S(1,n) &= S(-1,n) \\ S(1,1) &= S(1,-1) \\ S(1,1)|_0 &= 1.00 \\ S(2,n) &= 0 \\ S(1,7) &= S(1,8). \end{aligned}$$

The computer circuit for Eq (10) is shown in Fig. 6. As in Fig. 2, there is one integrating amplifier for each active cell. The solutions for the source cell obtained from the 56-cell and the 84-cell models are compared in Fig. 7. Evidently the approximations are not bad for small values of X .

For all the following work, the absolute error for values of $X > 1$ is large. To show the relative influence of the various parameters introduced, all of the solutions that follow will be shown relative to a reference solution. The reference solution will be that solution obtained for each model when the eddy diffusivity is held constant and the horizontal wind component V is zero. This type of reference does nothing to improve the accuracy of the solutions displayed but provides a convenient benchmark for observing the desired effect.

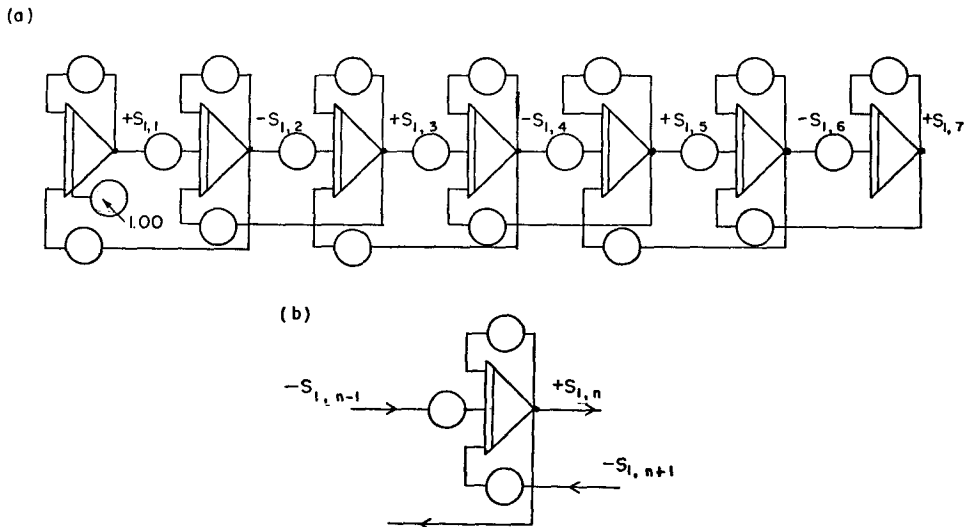


FIG. 6. Computing circuit for the first quadrant of the 56-cell model shown in (a). An integrating amplifier for a typical cell is shown in (b).

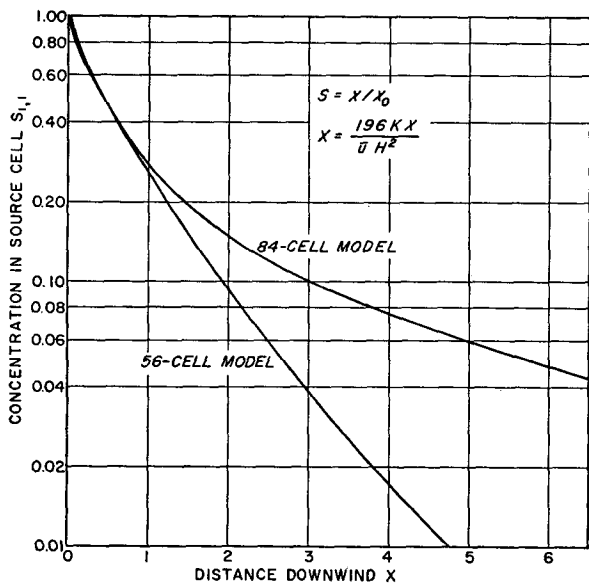


FIG. 7. Comparison of concentration plots for the source cell using the 84- and the 56-cell models with isotropic diffusion conditions.

C. Eddy diffusivity related to plume dimensions. Plume dimensions may influence the magnitude of the effective eddy diffusivity acting on the plume since, as the cloud grows, larger eddies are able to operate to diffuse the materials. The eddy diffusivity might be made a function of the plume size and of the power spectrum of eddies present. In the usual parabolic diffusion equation, the plume has no easily defined boundaries except those imposed upon it, such as the surface of the ground. Therefore the diffusivity cannot be related directly to

plume size but must be specified in some other manner. For example, it could be made proportional to the standard deviation of the concentration distribution taken perpendicular to the plume axis. If this distribution is normal, the standard deviation is inversely proportional to the central maxima or axial concentration, so that the diffusivity can be set inversely proportional to the axial plume concentration. Since the power spectra would never be continuous indefinitely, the diffusivity could not become infinite as the axial concentration went to zero but would reach some finite value and remain constant. In the finite difference model, the source is finite so that the diffusivity would increase from one small finite value to a larger one inversely as the concentration in the cell containing the source. Represent the diffusivity as $\varphi(S)K$ where K is the diffusivity for infinite plume dimensions and $\varphi(S)$ is a function of the axial concentration such that

$$0 < \varphi(S) \leq 1.00.$$

For example, set

$$\varphi(S) = 1 - 0.7S(1,1) \tag{11}$$

since $1.00 \geq S(1,1) \geq 0$. Eq (10) becomes

$$\left. \frac{dS}{dX} \right|_{1,n} = \varphi(S) [S(1,n+1) - 2S(1,n) + S(1,n-1)] - 0.7220 \varphi(S) S(1,n) \tag{12}$$

with the same boundary conditions as before. The computing circuit, shown partially in Fig. 8, is similar to that of Fig. 6 in principle. This one uses 3 amplifiers, 1 integrator and 2 summers, per cell to isolate all the

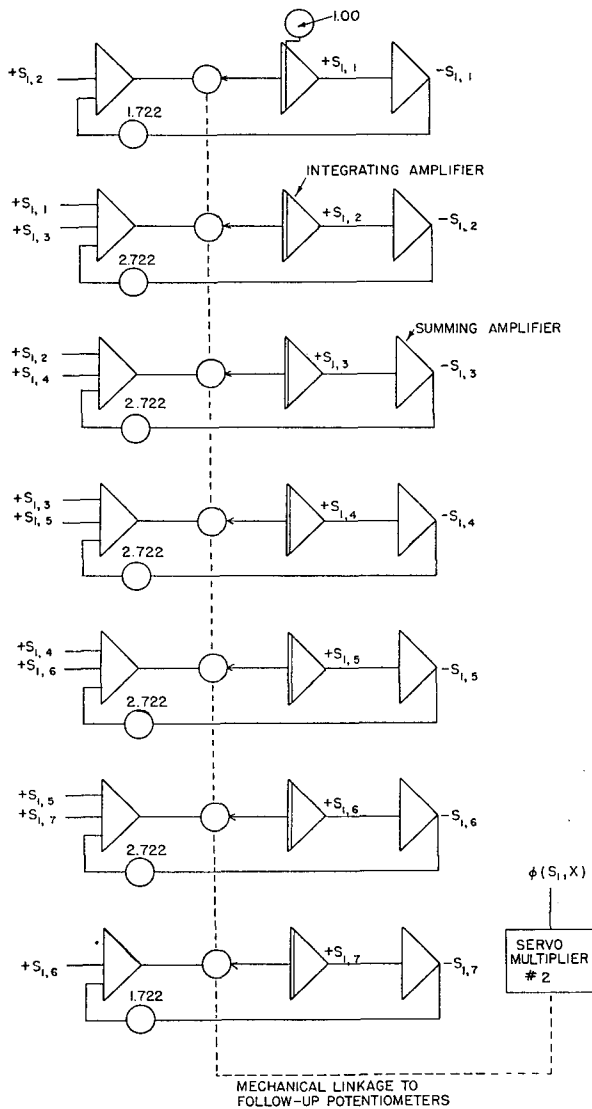


FIG. 8. Computing circuit for the first quadrant of the 56-cell model which permits the inclusion of special forms of the coefficient of eddy diffusivity.

inputs to the integrating amplifier. With this configuration, it is only necessary to introduce the modifying parameter $\varphi(S)$ once per cell.

Since $\varphi(S)$ is a function of the axial concentration, its form is determined by a feedback loop defined by Eq (11). The function $\varphi(S)$ is generated as the solution proceeds.

The computing circuits used in this problem are virtually identical with those of the next section. Therefore the description of the additional components required for the generation of $\varphi(S)$ and the presentation of the solutions will be deferred to that section.

D. Diffusion in transitional states. A problem of special interest arises when the trajectory of the diffusing plume crosses the boundary from one turbulent regime

to another. The physical model consists of a source located over land not far from the shore of a lake. The wind blows from the land out over the lake and the mechanical and perhaps the thermal turbulence decrease markedly as it does so. The associated diffusion is referred to in this research as diffusion in a transitional state; the inversion breakup fumigation (Hewson, 1945) is the result of a corresponding time transition in diffusion.

In the mathematical model, a change in the eddy diffusivity accompanies the transition from one turbulent regime to the other. This will be implemented by applying another modifying parameter $\varphi(X)$ to the constant K . The $\varphi(X)$ will be unity in the first regime and fall to some lesser value in the second. For the present preliminary study, this function was simulated directly on the computer to conform to an intuitive impression of what it should be without using a mathematical expression. It is possible to contrive a mathematical description, which is

$$\varphi(X) = 0.52 + 0.48 \{ [1 - h(X - X_1)] + \cos(X - X_1) \times [h(X - X_1) - h(X - X_1 - \pi/2)] \}, \quad (13)$$

where $h(a)$ is the unit step function which has the following properties

$$h(a) = 0, \quad a < 0 \\ = 1, \quad a \geq 0,$$

and X_1 is the value of X where the turbulence starts to decrease.

The diffusion equation is just Eq (12) with $\varphi(S)$ replaced with $\varphi(X)$. The computing circuit is also that of Fig. 8 and the circuit for generation of $\varphi(S)$ and $\varphi(X)$ is shown in Fig. 9.

The physical problems discussed in this section and in the previous one are different despite a somewhat deceptive similarity in the governing equation used. The differences between the problems are indicated in the form of the modifying parameter φ . It is only because of the similar way in which φ is implemented that the problems are handled together.

It is possible to introduce both effects in the problems. In this case, a new parameter will be defined such that $\varphi(S, X) = \varphi(S)\varphi(X)$. Fig. 9 shows how each of three functions is generated. When switch 1 is on -100 and switch 2 is closed, the output of amplifier 4 is $\varphi(S)$ as defined by Eq (11) and it passes through servomultiplier 1 unchanged to control servomultiplier 2. When switch 1 is on $\varphi(X)$ and switch 2 is open, the function $\varphi(X)$, generated by amplifiers 1, 2 and 3, controls servomultiplier 2. The function $\varphi(S, X)$ is generated when switch 1 is on $\varphi(X)$ and switch 2 is closed. The functions $\varphi(S)$, $\varphi(X)$ and $\varphi(S, X)$ are plotted in Fig. 10 as they were generated by the computer.

Solutions for $S(1,1)$, $S(1,2)$ and $S(1,3)$ are presented in Figs. 11, 12 and 13, respectively, for 4 cases: $\varphi=1$,

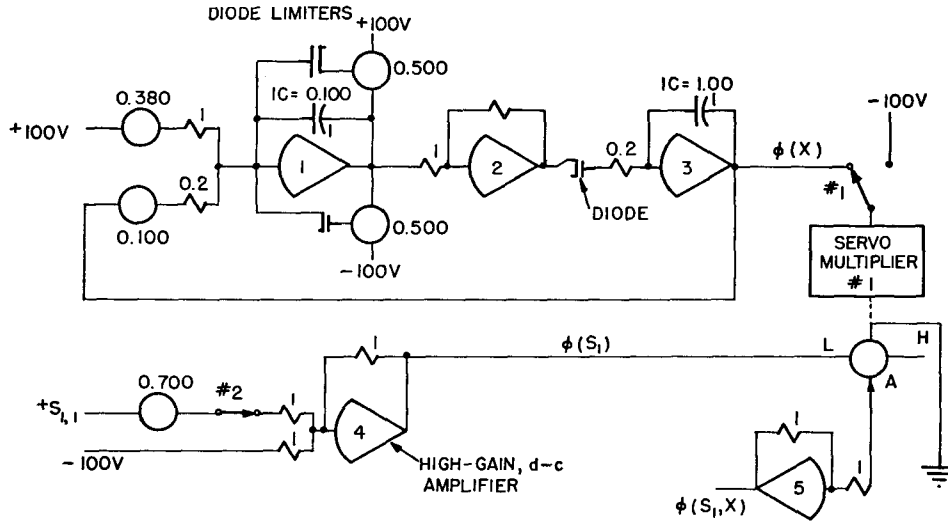


FIG. 9. Computing circuit for the generation of the special forms of the coefficient of eddy diffusivity.

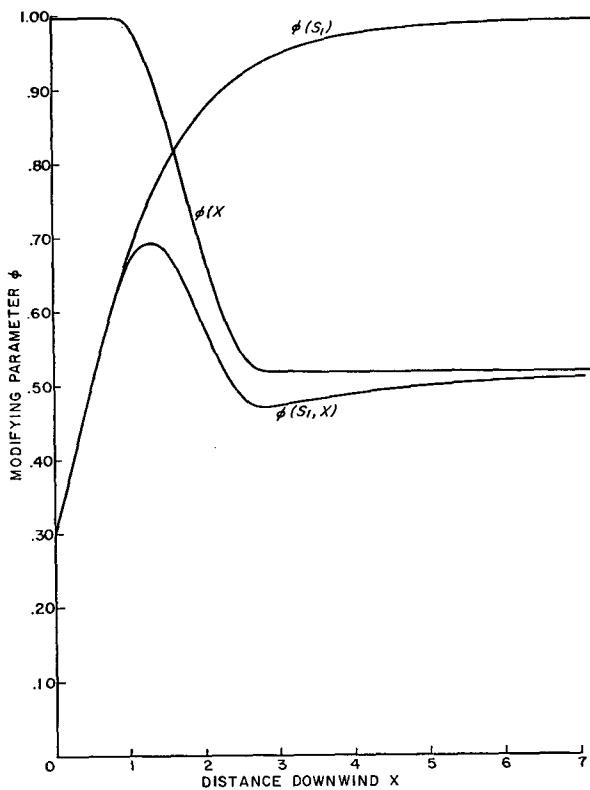


FIG. 10. Plot of the modifying parameters of the coefficient of eddy diffusivity.

$\varphi = \varphi(S)$, $\varphi = \varphi(X)$ and $\varphi = \varphi(S, X)$. The case $\varphi = 1$ is the reference solution. Each modifying parameter acts to change the scale in X , that is, the new solutions can be found by translation in X from the reference solution. This is shown best in Figs. 12 and 13 where the maxima

have been translated and expanded but the values of the maxima remain the same. The first modifying parameter $\varphi(S)$ is significantly different from unity only for small values of X so the greatest effect on the solutions should occur there. Each solution shows large translation for small values of X . The net effect of coupling the eddy diffusivity to cloud dimensions is to increase the concentration values for small X along the plume axis and to delay the occurrence of the maxima off the axis. The solutions for $\varphi(1)$ and $\varphi(S)$ do not converge for large X but reach a constant translation in X . But since the gradient is small for large X , the absolute value of the differences between the solutions is small.

Since the function $\varphi(X)$ can be determined independently, the solution could be found from the reference solution by plotting it on a new scale defined by

$$X^* = \int_0^X \varphi(X) dX.$$

The observed effect corresponds to this point of view in that $\varphi(X)$ has no effect on the solution for $X < 1$ but acts to translate the solution for $X > 1$.

E. Wind direction shear. The presence of wind direction shear in the diffusing layers causes the plume cross section to be skewed, and the amount of skewness can be determined by inserting terms in the diffusion equation for cross wind components. Eq (6) contains the nondimensional parameter $V = Hv/K$ for these cross wind components. Since the diffusion pattern is not symmetrical, it will not suffice to simulate only the first quadrant. In the interest of simplicity, a new 25-cell model is used as shown in Fig. 14. The source cell is 0, 3 and there are 15 active cells. Fig. 15 shows $V(Z)$, which is an exponential function of height, in the finite

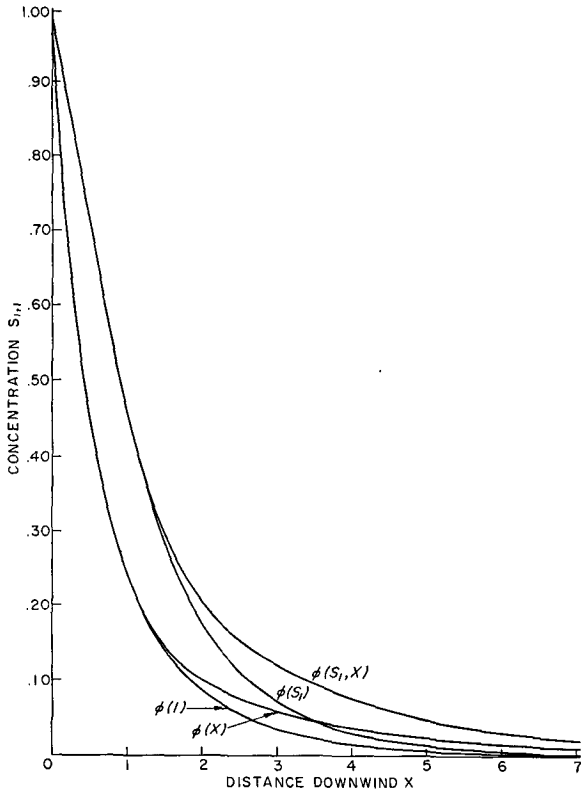


FIG. 11. Plot of the concentrations in the source cell as a function of the modifying parameter used.

difference model in relation to the downwind component Hu/K . The exponential function was chosen as an approximation to the lower part of the Ekman spiral. Eq (6) may be written

$$\frac{dS}{dX} \Big|_{m,n} = \frac{1}{25\Delta Y(m)} \left[\frac{S(m+1,n) - S(m,n)}{\Delta Y(m + \frac{1}{2})} - \frac{S(m,n) - S(m-1,n)}{\Delta Y(m - \frac{1}{2})} \right] - \frac{V_n}{50\Delta Y(m)} [S(m+1,n) - S(m-1,n)] + [S(m,n+1) - 2S(m,n) + S(m,n-1)], \quad (14)$$

where $X = 25\bar{x}$ and the boundary conditions are

$$\begin{aligned} S(-2, n) &= 0 \\ S(2, n) &= 0 \\ S(m, 0) &= S(m, 1) \\ S(m, 5) &= S(m, 6) \\ S(0, 3) \Big|_0 &= 1.00. \end{aligned}$$

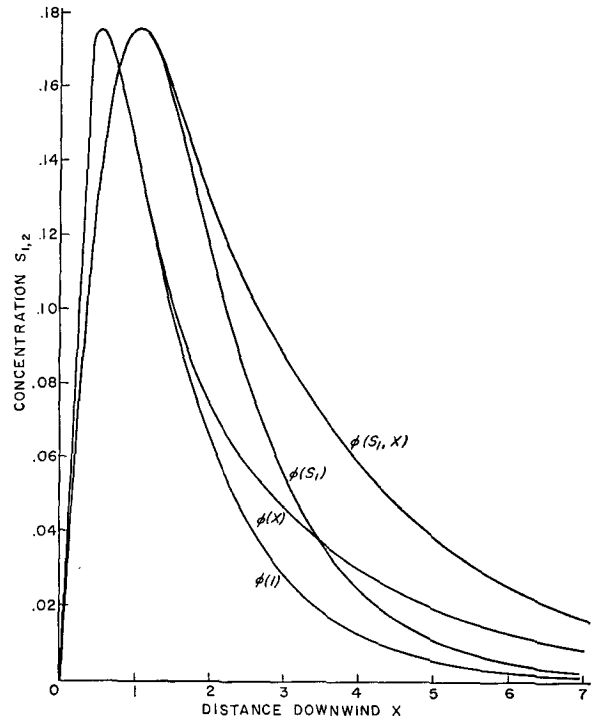


FIG. 12. Plot of the concentration in cell 1, 2 as a function of the modifying parameter used.

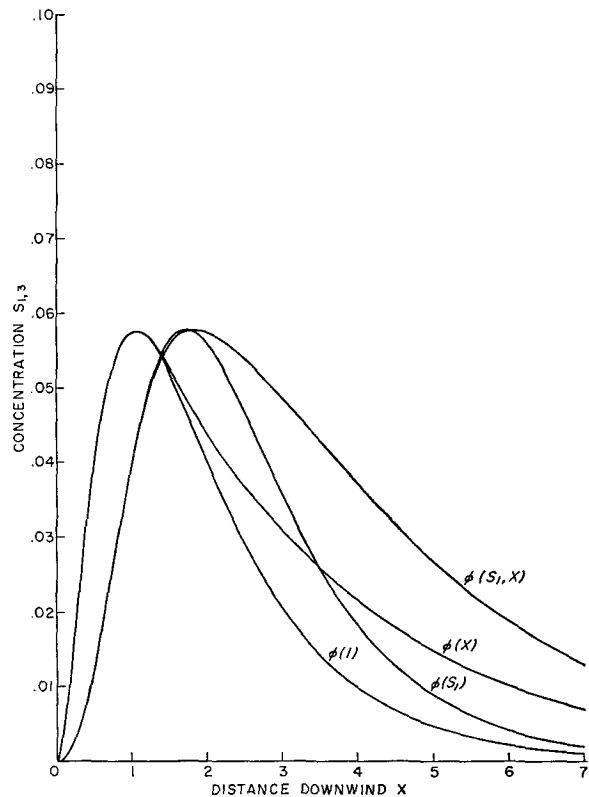


FIG. 13. Plot of the concentration in cell 1, 3 as a function of the modifying parameter used.

The computing circuit is shown in Fig. 16 and the solutions are in Figs. 18, 19 and 20. Each solution is compared to the reference solution, where $V(Z)=0$. We can compare the concentrations in the cells for two cases at some distance down-stream, say at $X=1$.⁴ The

⁴ In making this comparison, note that changes in wind direction were provided by adding v components while holding u constant which increased the magnitude of the total vector by an average 1.6 per cent. Since X is a function of u , we can compensate for this by evaluating the concentrations when $V \neq 0$ at $X=1$ and when $V=0$ at $X=1.016$.

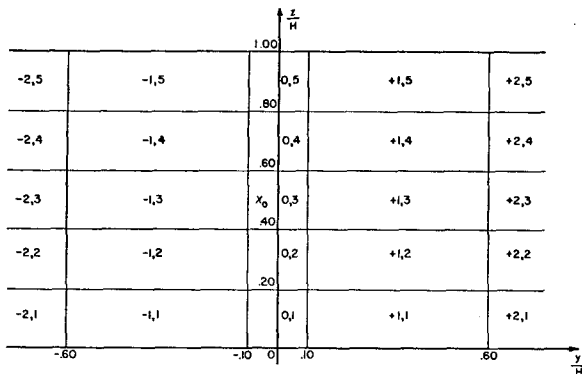


FIG. 14. The 25-cell, finite difference model of diffusion from a point source.

results, as shown in Fig. 17, indicate that the wind direction shear produces a marked skewness in the plume. The skewed plume is to be expected but a more interesting question is whether the average concentrations in the plume are reduced because of the skewness. Figs. 18, 19 and 20 indicate that the concentrations are reduced,

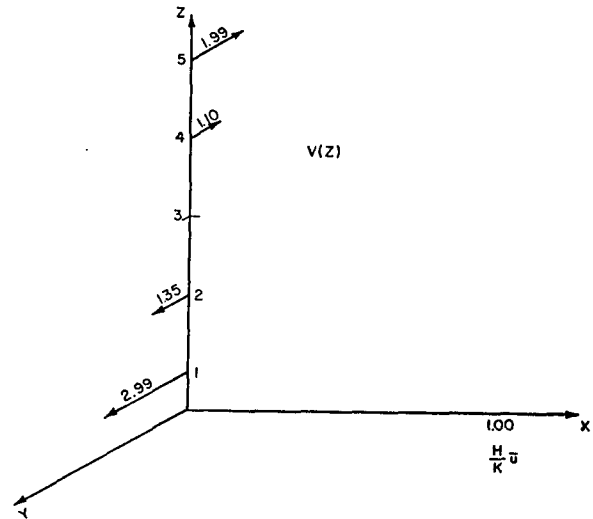


FIG. 15. A schematic of the wind shear component V as a function of height in the 25-cell finite difference model.

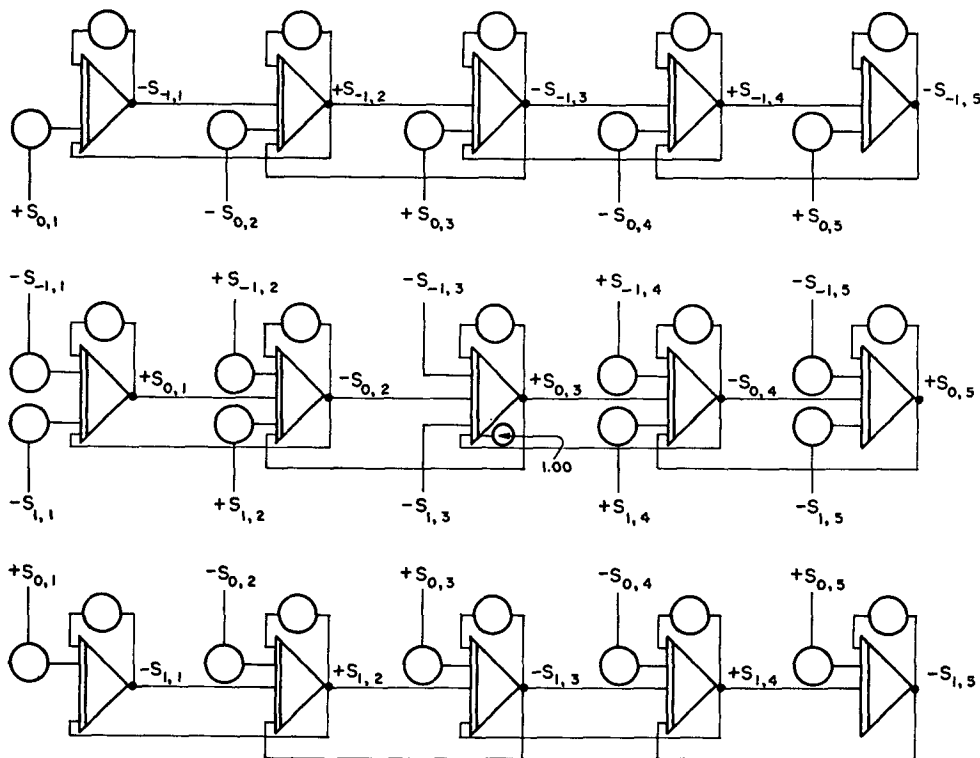


FIG. 16. Computing circuits for the 25-cell model for the case with wind shear.

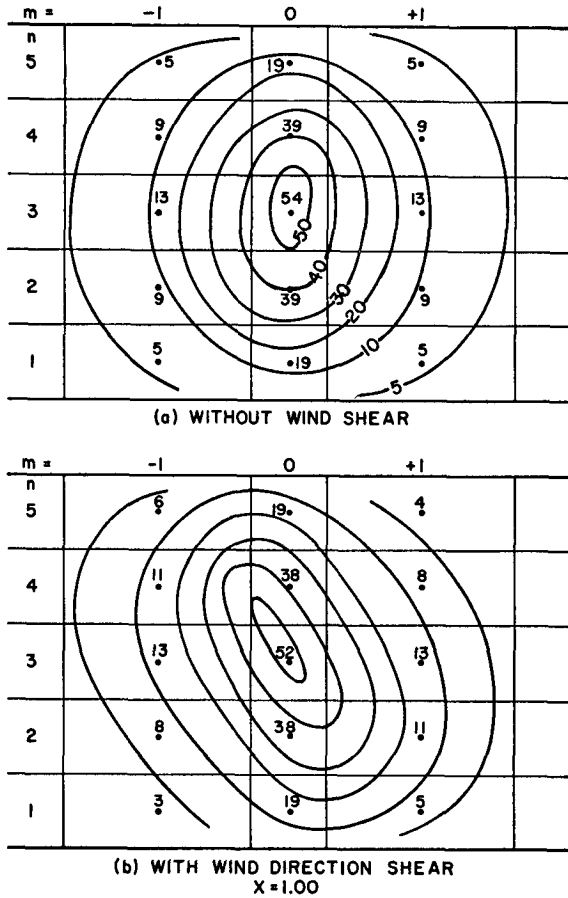


FIG. 17. Cross section of the plume at $X=1$ showing lines of constant concentration in arbitrary units.

by about 4 per cent in the center of the plume at $X=1$. The integrated concentration over the plume at $X=1$ was reduced about 2 per cent. Thus it seems valid to conclude that wind direction shear does increase the diffusing properties of the atmosphere. It is planned to analyze the influence of wind direction shear in concentrations downwind from a continuous point source using an analog computer of much greater capacity.

F. Large-scale eddies. The presence of large-scale eddies or, since we are considering the steady state, a standing wave in the horizontal wind components can be represented as a sinusoid $v = -a \cos bx$. A stationary plume might be an example of this kind of process. The small-scale eddies which operate to diffuse the plume are represented by the coefficient of eddy diffusivity, whereas the large-scale eddies act only to transport the plume in the y -direction.

Equipment limitations at the time of the research dictated the choice of a more coarse finite difference model as shown in Fig. 21. The mathematical model, based on Eq (6), is

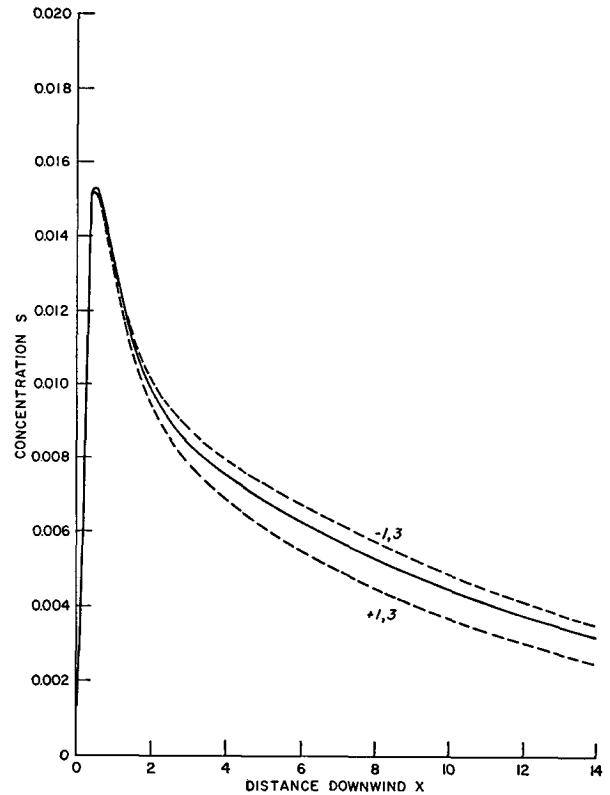


FIG. 18. Comparison of the concentration plots for cells to the right and the left of the source cell in the presence of wind shear.

$$\left. \frac{dS}{dX} \right|_{m,n} = 9[S(m+1,n) + S(m-1,n) + S(m,n+1) + S(m,n-1) - 4S(m,n)] - \frac{3}{2}V(X)[S(m+1,n) - S(m-1,n)], \quad (15)$$

where $V(X) = -Ha/K \cos BX$ and the boundary conditions are

$$\begin{aligned} S(2,n) &= S(-2,n) = 0 \\ S(0,3)|_0 &= 1.00 \\ S(m,1) &= S(m,2) \\ S(m,5) &= S(m,4) \end{aligned}$$

and $\Delta Y = \Delta Z = 1/3$ for the active cells. If we set $5A = Ha/6K$, Eq (15) becomes

$$\begin{aligned} \left. \frac{dS}{dX} \right|_{m,n} &= \frac{1}{10} [S(m,n-1) - 4S(m,n) + S(m,n+1) \\ &+ \{1 + 5A \cos BX\} S(m+1,n) \\ &+ \{1 - 5A \cos BX\} S(m-1,n)], \quad (16) \end{aligned}$$

where $X = 90\bar{x}$.

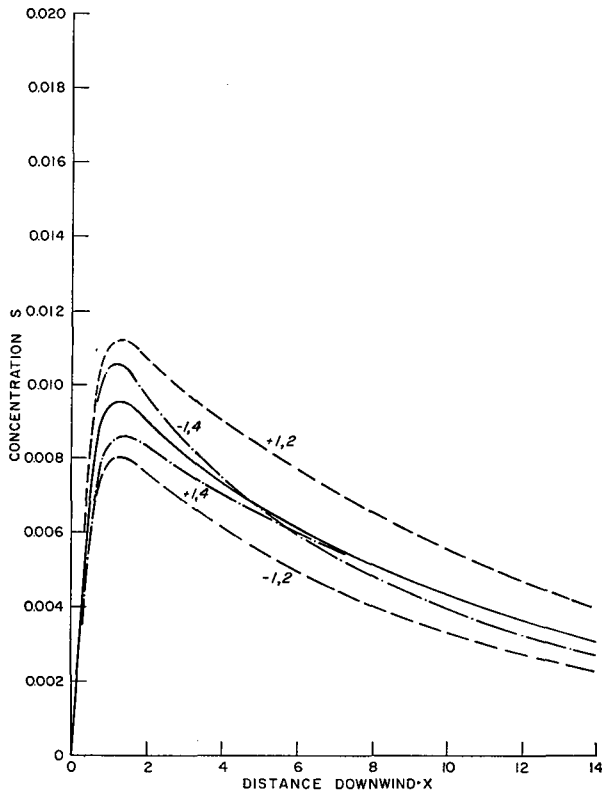


FIG. 19. Concentration plots for some cells in the 25-cell model in the presence of wind shear.

The constants A and B were given the values $1/5$ and 3 , respectively, so that $V(X) = -6 \cos 3X$ or $v(x) = -(6K/H) \cos(270Kx/uH^2)$. The maximum displacement of the plume due to the variable cross wind component can be found from the relation

$$\frac{dY}{dX} = \frac{V(X)}{90}$$

$$Y = \frac{1}{90} \int V(X) dX = -\frac{1}{45} \sin 3X.$$

Thus the maximum displacement is $\pm 1/45$ or ± 0.0222 . The computing circuit is shown in Figs. 22 and 23, and a typical cell is shown in Fig. 24. The solutions are plotted in Figs. 25, 26 and 27 along with the reference solution.

This system exhibits a phenomena like resonance in a forced second-order system. It is not pure resonance but the system does respond markedly to changes in frequency of the cross wind component. Changes in amplitude do not affect the qualitative nature of the solution.

The plume meander lags behind the cross wind components. The point at which the plume axis crosses the

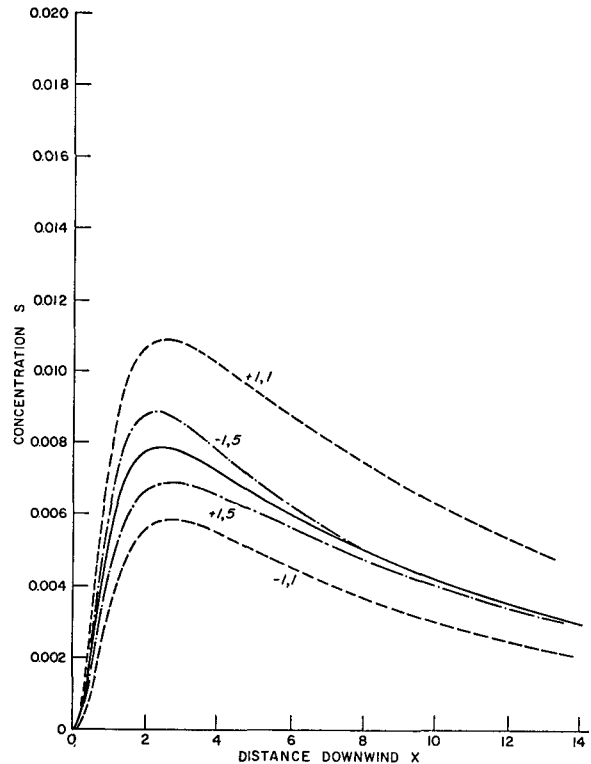


FIG. 20. Concentration plots for some cells in the 25-cell model in the presence of wind shear.

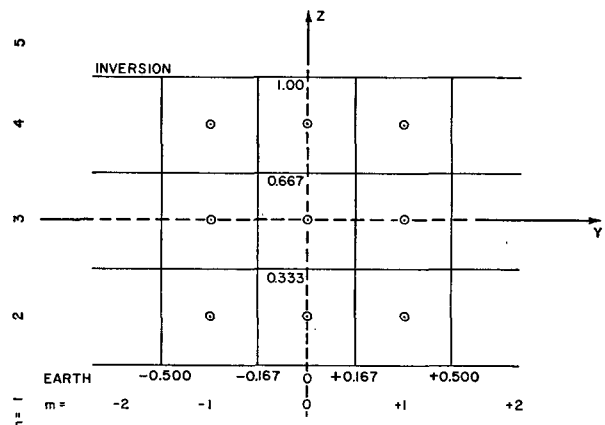


FIG. 21. The 15-cell finite difference model of diffusion from a point source for use in the case of diffusion in the presence of large scale eddies.

middle cell can be found by noting the point where concentration of opposite pairs of cells is equal. This occurs for $x=1.506, 2.448,$ and 3.531 , while the cross wind goes to zero at $X=1.047, 2.094$ and 3.141 . The phase lag is not constant for the above three points but is 78.9 deg, 60.9 deg and 67.1 deg, respectively.

It is of interest to compare the concentrations in the plume, for sampling periods short enough to avoid

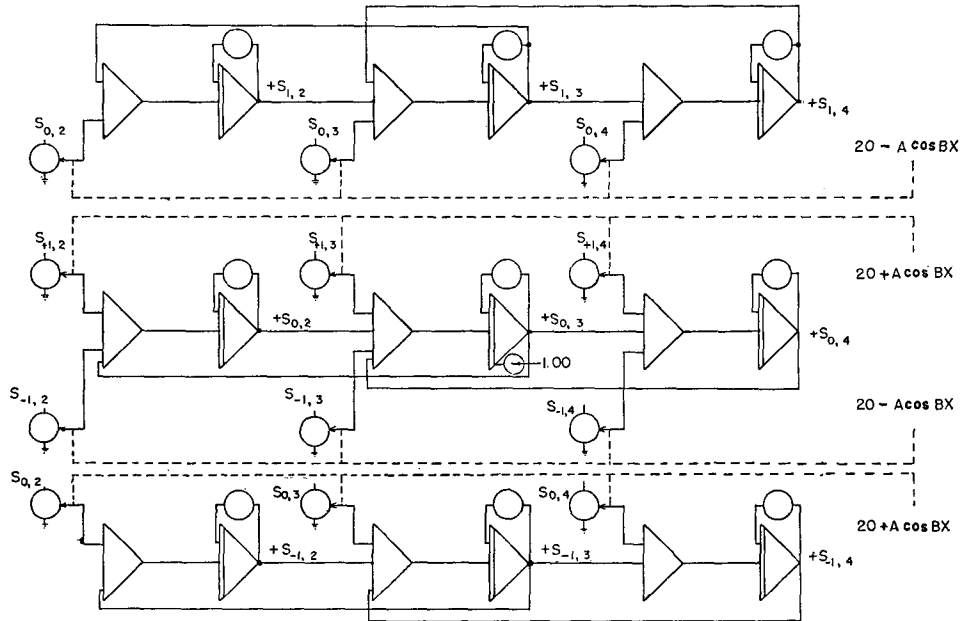


FIG. 22. Computing circuit for the 15-cell model including provision for variation of the horizontal wind component.

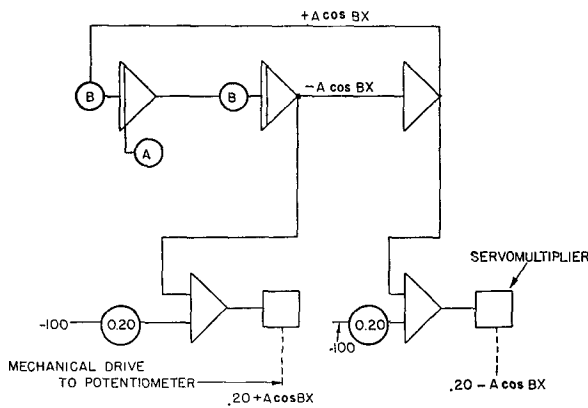


FIG. 23. Computing circuit for the generation of the sinusoidal horizontal wind component.

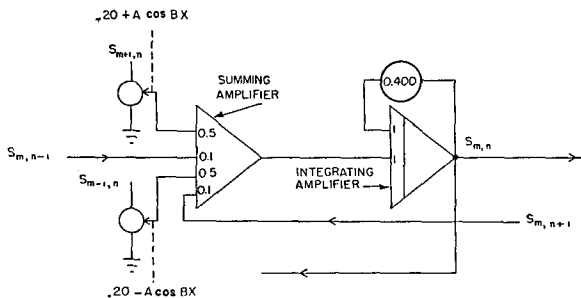


FIG. 24. Typical cell from the circuit of Fig. 21.

plume shifting, when it meanders with when it does not. At an arbitrary point downwind, at $X=1.6$, the total concentration reported in the case with no meander was 16 per cent higher than in the case where the plume meanders. As shown in the appendix, this decrease in concentration in the meandering plume is due entirely to the longer path length followed by the plume.

If one knew the total concentration across a straight plume as a function of distance downwind, one could then compute the long-term concentration at a station subjected to a plume in meandering but otherwise identical conditions. The calculations may be so tedious as to be impractical since they would involve computing the length of the trajectories over the given interval, adjusting the concentration and integrating them.

It would still be of interest to perform this calculation on the computer using random large-scale eddies, and it is intended that this topic will be the subject of a future analysis.

G. A possible combination of two of the models. Two of the models presented above are related to some extent. The model in which eddy diffusivity increases with the plume dimensions can be related to that including large-scale eddies. In the first case, the complete spectrum of eddies can be included and the effect on the plume partially determined. The solution is partially complete in that, while the diffusing effects of all the eddies are included, the transport due to eddies much larger than the plume dimensions is neglected. The model simply ignores eddies of a given scale until the plume dimensions grow to that scale. The transport

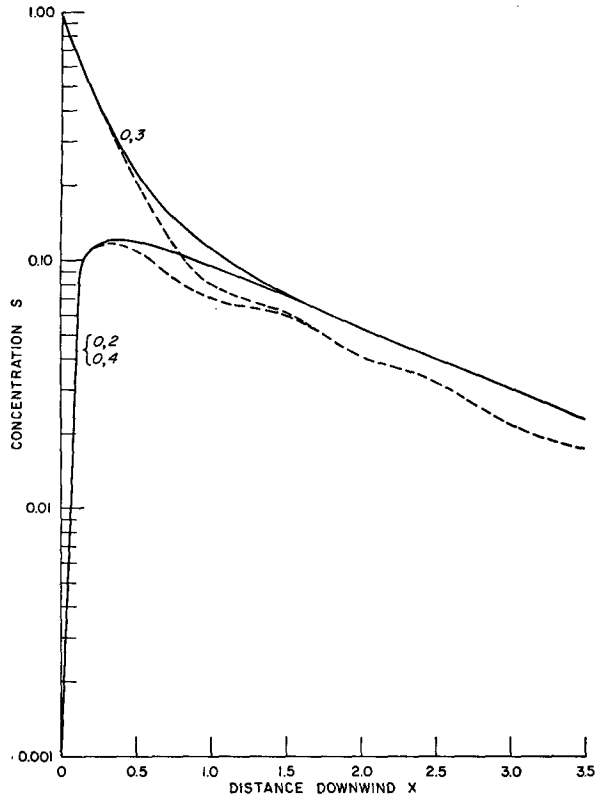


FIG. 25. Plot of the concentrations for cells 0, 2; 0, 3; and 0, 4 in the presence of large-scale eddies.

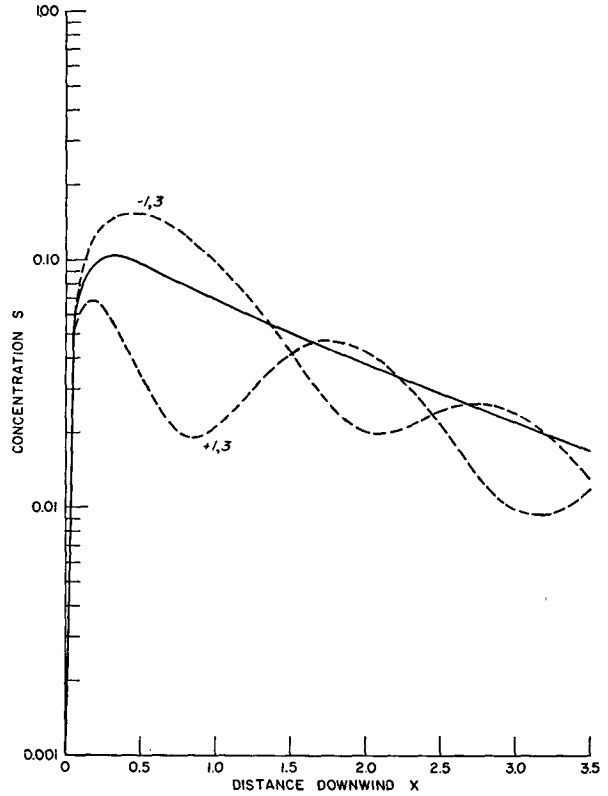


FIG. 26. Plot of the concentration for cells -1, 3 and +1, 3 in the presence of large-scale eddies.

phenomenon is shown in the latter model where the large-scale eddies are treated as a wind component, but here they contribute nothing to the diffusion process no matter how large the cloud becomes.

A combination of the two models might be an improvement. Let the wind components represent eddies larger than the plume while all smaller eddies act through the eddy diffusivity. The wind components would become smaller with distance downstream whereas the eddy diffusivity would increase. The wind components incorporated in the model are defined as averages, thus raising the question of how much they should be allowed to fluctuate or to possess time- or distance-variant properties. An averaged wind speed could be defined as the average or mean value obtained by the use of a sampling time just large enough to exclude all the turbulent eddies which contribute to the diffusion process. If we allow the assumption that the scale of eddies involved depends upon the scale of the plume, then the sampling time in the above definition would depend upon the plume size also. The wind-speed components could be represented as a Fourier series whose higher-frequency components are gradually eliminated as the plume grows, and conversely, the coefficient of eddy diffusivity would increase as more turbulent eddies were added to its domain. This is a

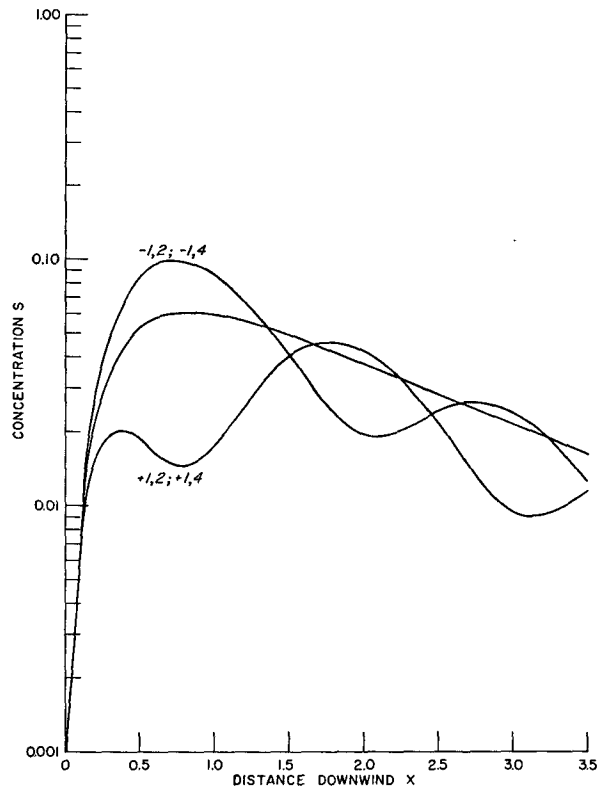


FIG. 27. Plot of the concentrations for cells -1, 2; -1, 4; and +1, 4 in the presence of large-scale eddies.

rather involved model even for analog computation and no attempt as yet has been made to set it up.

4. Summary and conclusions

As the model has become more complicated, it has been necessary to use fewer cells and to tolerate greater error. The amount of equipment needed is proportional to the number of cells and to the complexity of the model, and all the research described here was done on one machine with a very limited amount of computing equipment. The direct way to reduce error, then, is to use a larger machine which would permit simulation of more cells. The errors are proportional to the fourth partial space derivative so that the error can be reduced by solving for a function related to the solution which possesses a smaller fourth derivative. Such a function could be found by perturbation techniques.

The parabolic diffusion equation has been shown to be of general utility in the variety of problems covered. It is a model which is well adapted to analog computation. With sufficient equipment the actual programming seldom presents any difficulty even in the most involved problems discussed here.

The trapping situation was used throughout this report to limit the scope of the research, and to facilitate handling the problems on a computer of given size. Extension of these methods to nontrapping situations can be readily done using the technique reported earlier.

Acknowledgment. The authors wish to acknowledge the wholehearted cooperation and assistance of Mrs. Anne C. Rivette.

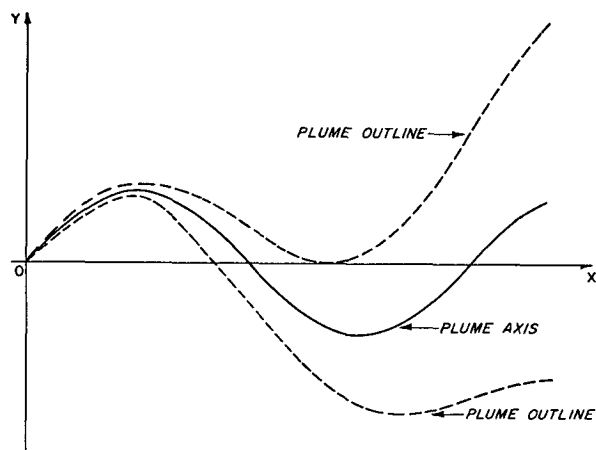


FIG. 28. Schematic of the fluctuating plume model showing the sinusoidal nature of the plume axis.

APPENDIX

In the case where the meandering plume was treated, there were two possible mechanisms which could affect the diffusion of the plume. The one noted in the main body of the report was the increased path length of the trajectory. The other is that large-scale eddies might change the shape of the plume, thereby influencing the diffusion process. An attempt was made to evaluate this mechanism by correcting for the first one.

When there is a cross wind which causes meandering, the magnitude of the total wind vector and the path length along the plume axis, as shown in Fig. 28, has been increased. To compensate for this, the concentration for no cross wind should be taken at a point further downstream in inverse proportion to the relative decrease in the magnitude of the wind vector. Taking the first zero crossing, at $X_1=1.506$, the compensating factor is

$$X_2 = X_1 \sqrt{1 + \sin^2 BX_1}$$

where

$$\begin{aligned} \overline{\sin^2 BX} &= \frac{1}{X_1} \int_0^{X_1} \sin^2 BX dX \\ &= \frac{1}{2BX_1} [BX_1 - \sin BX_1 \cos BX_1] \\ &= 0.4790. \end{aligned}$$

Then $X_2 = 1.506 \sqrt{1.479} = 1.831$. The following table gives the concentration in both cases. Evidently the plume shape is a little different since the individual cells do not report identical concentrations, but the sum of the concentrations for all the cells is not significantly different.

TABLE A-1. Comparison of plume concentrations for the meandering plume and the straight plume.

Cell	Straight plume $X=1.831$	Meandering plume $X=1.506$
0,2	0.0595	0.0599
0,3	0.0596	0.0617
0,4	0.0595	0.0599
-1,2	0.0412	0.0406
-1,3	0.0422	0.0420
-1,4	0.0412	0.0406
+1,2	0.0412	0.0406
+1,3	0.0422	0.0420
+1,4	0.0412	0.0406
Total concentration	0.4278	0.4279

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